> Peter Siepmann<sup>1</sup>, Christopher Martin<sup>2</sup>, Natalio Krasnogor<sup>1</sup>, Philip Moriarty<sup>2</sup>

Condensed Matter and Materials Physics 20<sup>th</sup> April, University of Exeter



School of Computer Science & IT<sup>1</sup> School of Physics & Astronomy<sup>2</sup>



### **Overview**



Physical background



Nanoparticle simulation details



• A brief overview of Genetic Algorithms



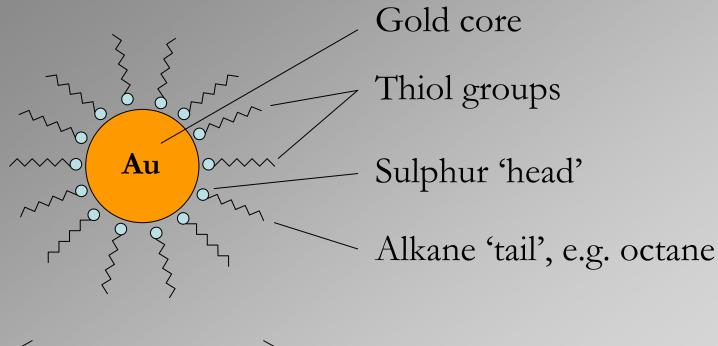
Results from initial trials



Conclusions & further work



### **Thiol-passivated Au nanoparticles**

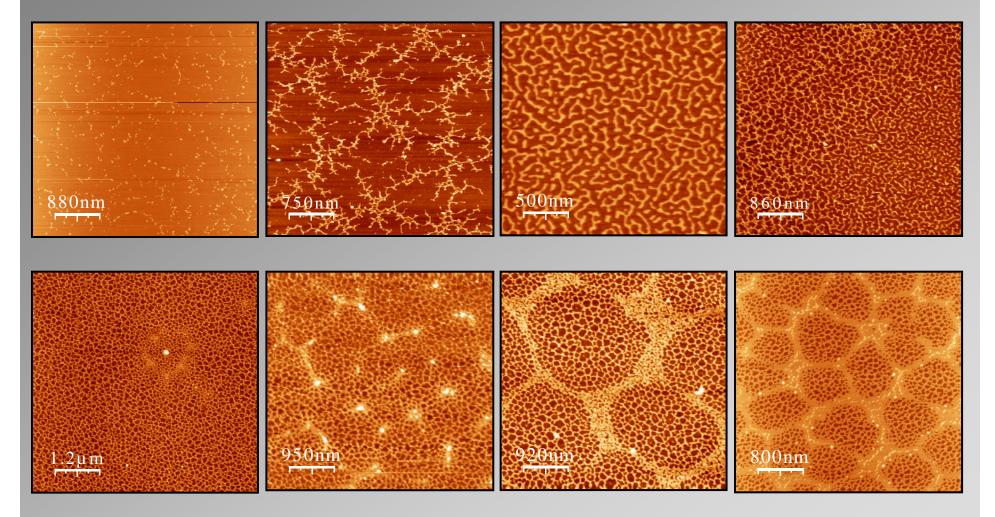


~3nm

Dispersed in toluene, and spin cast onto native-oxide-terminated silicon



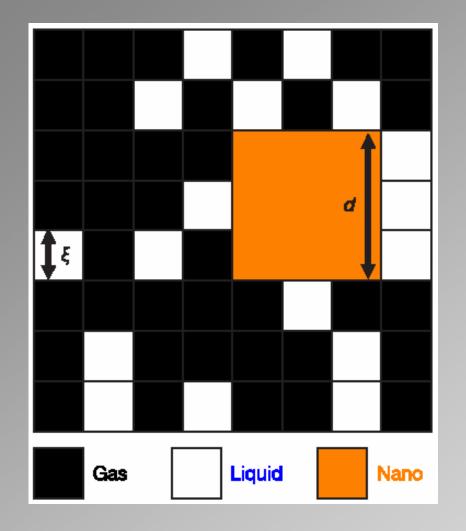
# Au nanoparticles: Morphology



AFM images taken by Matthew O. Blunt, Nottingham



### **Nanoparticle Simulations**



Solvent is represented as a twodimensional lattice gas

Each lattice site represents 1nm<sup>2</sup>

Nanoparticles are square, and occupy nine lattice sites

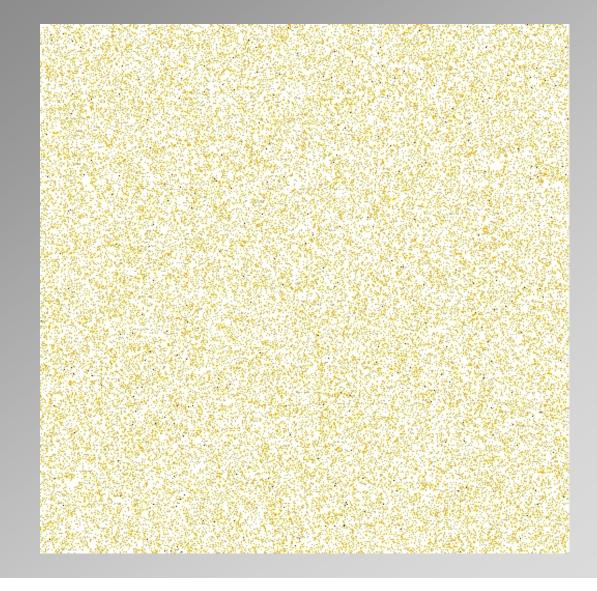
Based on the simulations of Rabani et al. (*Nature* **2003**, *426*, 271-274). Includes modifications to include next-nearest neighbours to remove anisotropy.



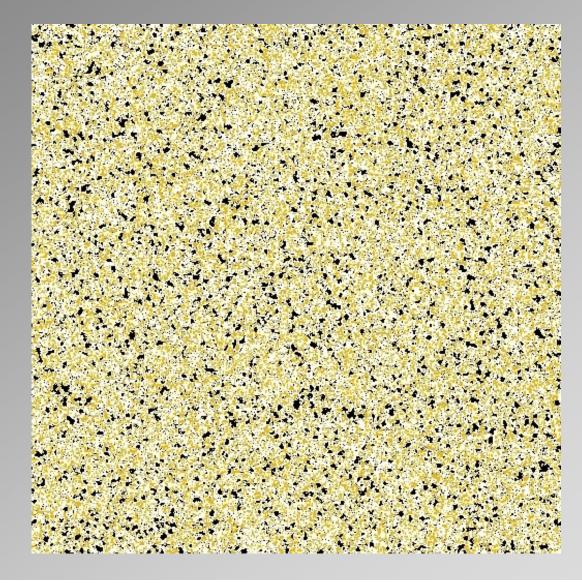
- The simulation proceeds by the Metropolis algorithm:
  - Each solvent cell is examined and an attempt is made to convert from liquid to vapour (or vice-versa) with an acceptance probability  $p_{acc} = \min[1, \exp(-\Delta H/k_BT)]$
  - Similarly, the particles perform a random walk on wet areas of the substrate, but cannot move into dry areas.
  - The Hamiltonian from which  $\Delta H$  is obtained is as follows:

$$H = -\varepsilon_l \sum_{\langle ij \rangle} l_i l_j - \varepsilon_n \sum_{\langle ij \rangle} n_i n_j - \varepsilon_{nl} \sum_{\langle ij \rangle} n_i l_j - \mu \sum_i l_i$$

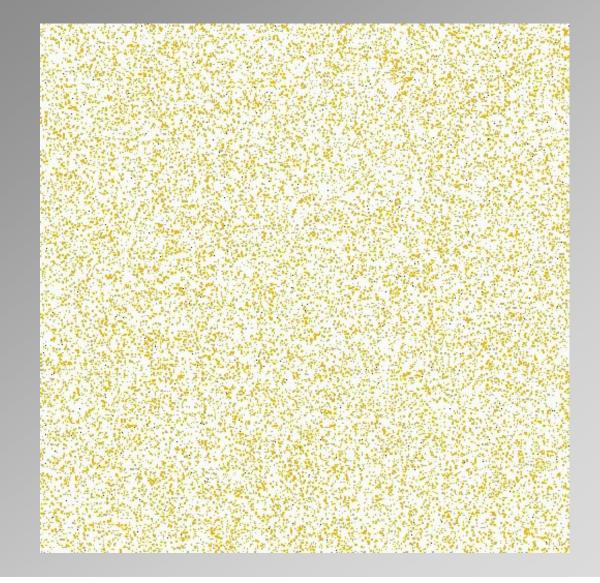














# A brief overview of Genetic Algorithms global optimum Motivation - optimisation problems - large search space - inspired by Darwinian evolution - area covered? - degree of order? - similarity to target pattern? 1.05 22 0.25 1.0 4.5 fitness function simulator fitness genotype

phenotype

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TIME

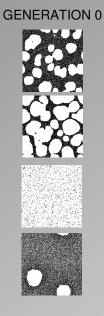
# A brief overview of Genetic Algorithms

#### **Evolution**

Recombination (mating)
e.g. exchanging parameters
*'combine the best bits of each parent'*

- Mutation

e.g. altering the value of a parameter at random with some small probability





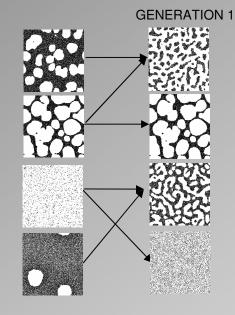
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GENERATION 2

TIME



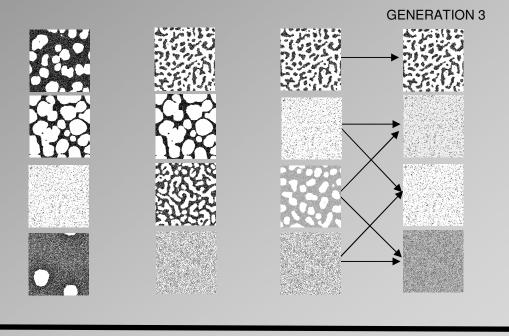
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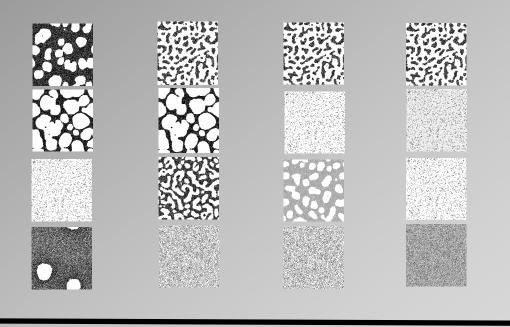
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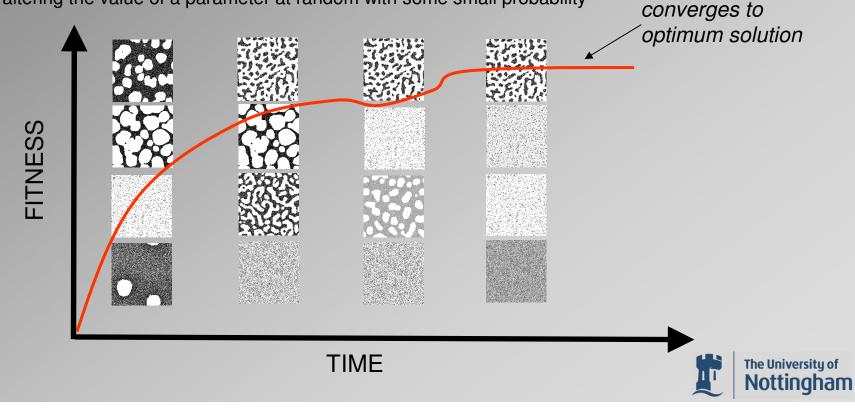
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# **Evolving towards a target pattern**

Fitness function:

"How similar is this pattern to the target pattern we are trying to recreate?"

How do we measure this?

# **The Universal Similarity Metric**

is a measure of similarity between two given objects,  $o_1$  and  $o_2,$  in terms of information distance:

 $d(o_1, o_2) = \frac{\max\{K(o_1 | o_2), K(o_2 | o_1)\}}{\max\{K(o_1), K(o_2)\}}$ 

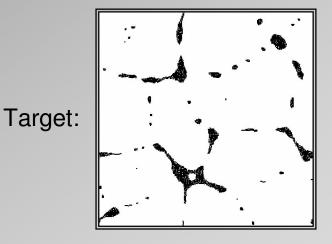
where K(0) is the Kolmogorov complexity:

K(o): The length of the shortest program for computing o by a Turing machine K(o<sub>1</sub>lo<sub>2</sub>): How much (more) information is needed to produce object  $o_1$  if one already knows object  $o_2$ 

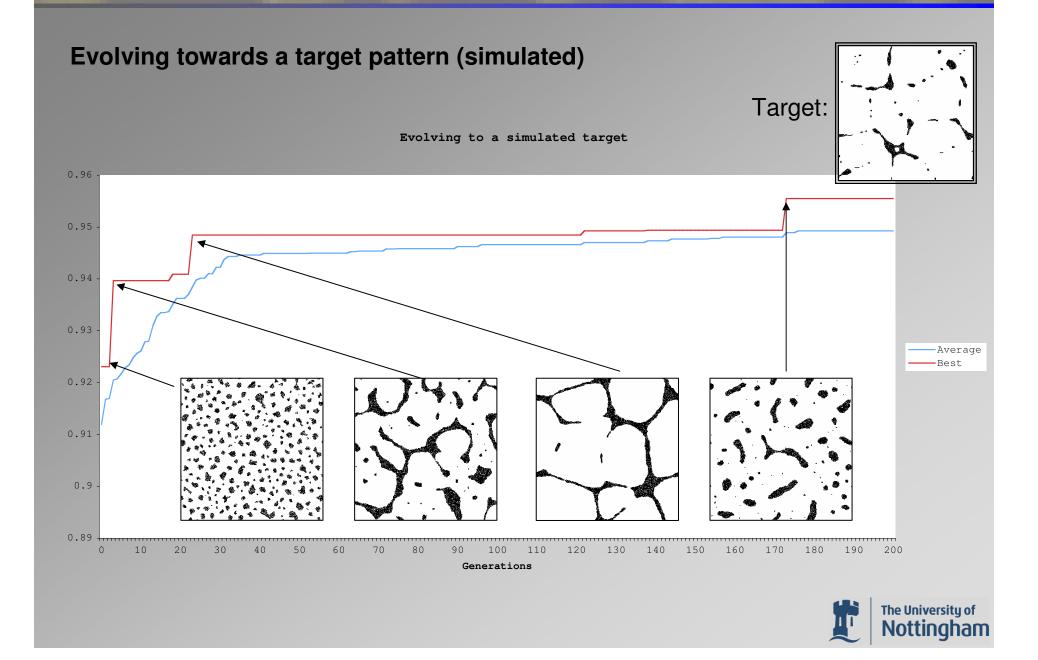


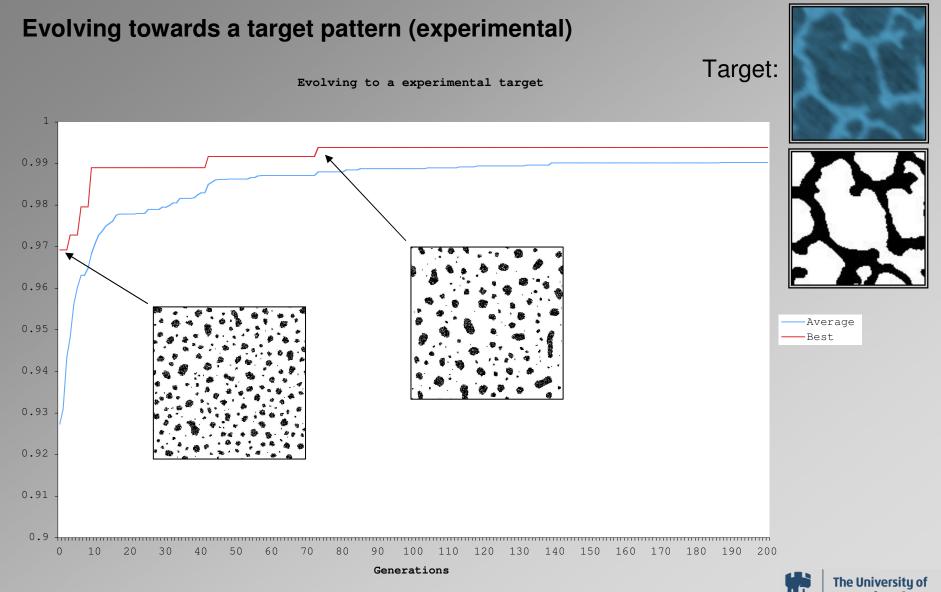
# **Evolving towards a target pattern (simulated)**

- Selected a target image from simulated data set
- Initialised GA
  - Roulette Wheel selection
  - Uniform crossover (probability 1)
  - Random reset mutation (probability 0.3)
  - Population size: 10
  - Offspring: 5
  - $\mu$  +  $\lambda$  replacement
- Ran the GA for 200 iterations
  - on a single processor server, run time ≈ 5 days
  - using Nottingham's cluster (up to 1024 nodes), run time ≈ 12 hours









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# **Conclusions and further work**

- we can evolve target simulated behaviour using a GA with the USM
- work continues to improve the evolution of experimental behaviour
- use of more introspective fitness functions *e.g. Minkowski functionals* 
  - open ended (multiobjective) evolution
    - e.g. "evolve a pattern with as many large spots as possible in as ordered a fashion as possible"
- parameter investigations
  - larger populations
- full fitness landscape analysis



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