

# A Constructive Hybrid Algorithm for Crew Pairing Optimization

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# Overview

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- ACO for Set Covering and Set Partitioning Problems
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# Introduction

- Set Partitioning Problem (SPP) is a type of problem that can model different real life situations: for example **Crew Pairing**
- There exist problems for which the pure **ACO Constructive Metaheuristic** is of limited effectiveness: very strongly constrained problems like SPP
- We explore the addition of a lookahead mechanism to the ACO algorithm for solving SPP. Applying these **Hybrid Algorithms** for solving standard benchmarks from Beasley's ORLIB (NorthWest Airline instances)

# Set Partitioning Problem

- SPP is the problem of partitioning a given set into mutually independent subsets while minimizing a cost function defined as the sum of the costs associated to each of the eligible subsets
- Its importance derives from the fact that many real life situations can be modeled as SPP, and in fact many combinatorial optimization problems (such as, crew scheduling, vehicle routing, project scheduling, and warehouse location problems, to name a few) can be modeled as SPP with maybe some additional constraints
- In SPP we are given a  $m \times n$  matrix  $A = (a_{ij})$  in which all the matrix elements are either zero or one. Additionally, each column is given a non negative cost  $c_j$
- We say that a column  $j$  covers a row  $i$  if  $a_{ij} = 1$
- Let  $x_j$  denotes a binary variable which is one if column  $j$  is chosen and zero otherwise

# Set Partitioning Problem Example

	$x_1$	$x_2$	$x_3$	$x_4$
1	1	1	0	1
2	0	1	0	0
3	0	0	1	1

Where

$$C_1 = 10$$

$$C_2 = 20$$

$$C_3 = 30$$

$$C_4 = 40$$

*Minimize*

$$10x_1 + 20x_2 + 30x_3 + 40x_4$$

*Subject to*

$$x_1 + x_2 + x_4 = 1$$

$$x_2 = 1$$

$$x_3 + x_4 = 1$$

# Set Partitioning Problem Formulation

$$\text{Min}(z) = \sum_{j=1}^n c_j x_j$$

*Subject to :*

$$\forall i \rightarrow \sum_{j=1}^n a_{ij} x_j = 1$$

$$\forall j \rightarrow x_j \in \{0,1\}$$

A pairing is a sequence of flights to be covered by a single crew over a 2 to 3 day period

Pairing j	Flight Sequence	Cost \$
1	101-203-406-308	2900
2	101-203-407	2700
3	101-204-305-407	2600
4	101-204-308	3000
5	203-406-310	2600
6	203-407-109	3150
7	204-305-407-109	2550
8	204-308-109	2500
9	305-407-109-212	2600
10	209-109-212	2050
11	402-204-305	2400
12	402-204-310-211	3600
13	406-308-109-211	2550
14	406-310-211	2650
15	407-109-211	2350

Defining the decision variable  $x_j$  equal to 1 if paring j is chosen and 0 otherwise. Each flight must be covered.

$$\text{Minimize } 2900x_1 + 2700x_2 + 2600x_3 + 3000x_4 + 2600x_5 + 3150x_6 + 2550x_7 + 2500x_8 + 2600x_9 + 2050x_{10} + 2400x_{11} + 3600x_{12} + 2550x_{13} + 2650x_{14} + 2350x_{15}$$

*Subject to*

$$x_1 + x_2 + x_3 + x_4 = 1 \text{ (flight 101)}$$

$$x_6 + x_7 + x_8 + x_9 + x_{10} + x_{13} + x_{15} = 1 \text{ (flight 109)}$$

$$x_1 + x_2 + x_5 + x_6 = 1 \text{ (flight 203)}$$

$$x_3 + x_4 + x_7 + x_8 + x_{11} + x_{12} = 1 \text{ (flight 204)}$$

$$x_{12} + x_{13} + x_{14} + x_{15} = 1 \text{ (flight 211)}$$

$$x_9 + x_{10} = 1 \text{ (flight 212)}$$

$$x_3 + x_7 + x_9 + x_{11} = 1 \text{ (flight 305)}$$

$$x_1 + x_4 + x_8 + x_{10} + x_{13} = 1 \text{ (flight 308)}$$

$$x_5 + x_{12} + x_{14} = 1 \text{ (flight 310)}$$

$$x_{11} + x_{12} = 1 \text{ (flight 402)}$$

$$x_1 + x_5 + x_{13} + x_{14} = 1 \text{ (flight 406)}$$

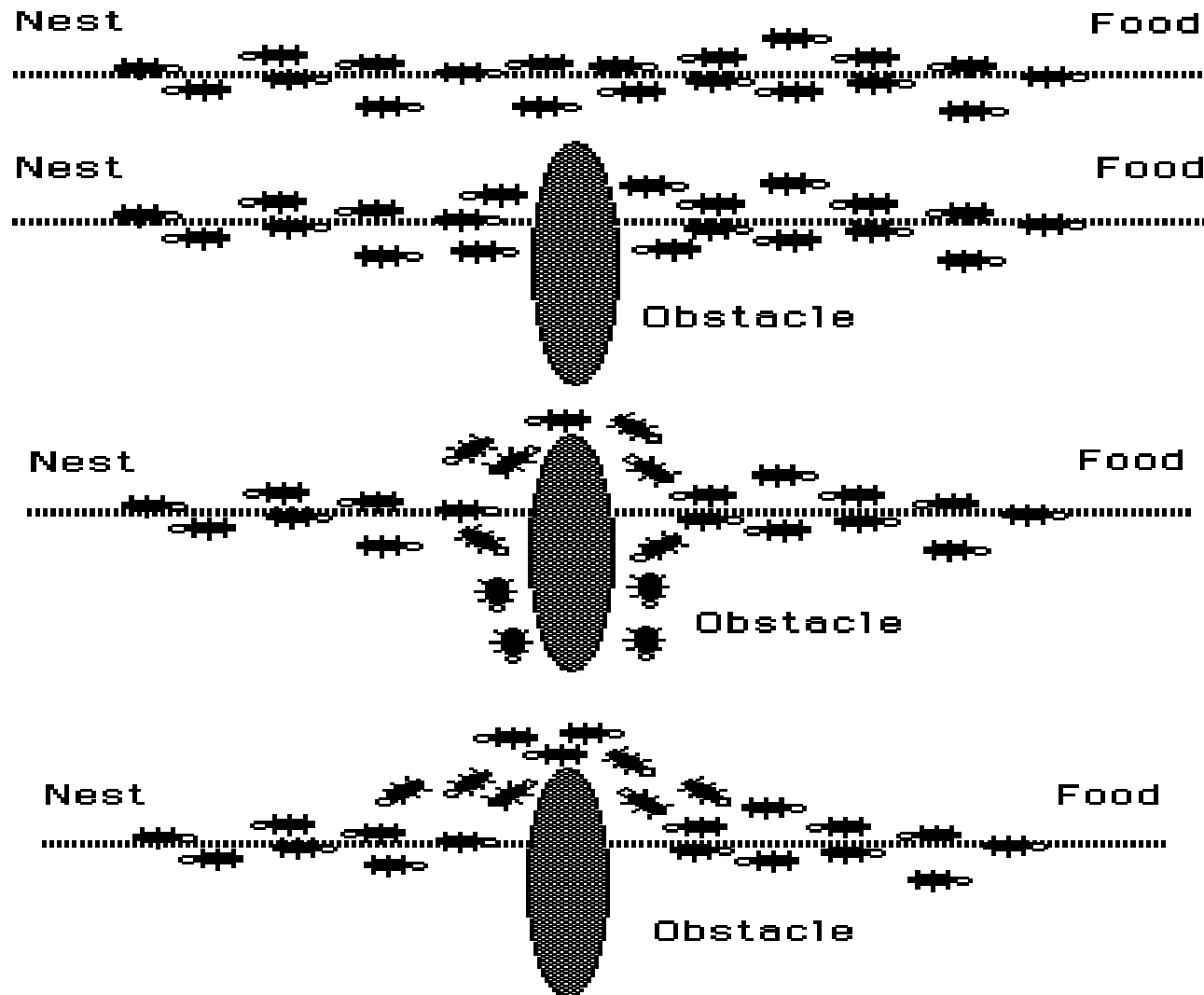
$$x_2 + x_3 + x_6 + x_7 + x_9 + x_{15} = 1 \text{ (flight 407)}$$

$$x_j = 0 \text{ or } 1; \forall j = 1, \dots, 15$$

# Ant Colony Optimisation (ACO)

- A metaheuristic search process based on the foraging behaviour of ant colonies
  - A number of agents, called (artificial) ants, build up solutions to the problem at hand
  - They deposit pheromone on each element they choose/visit
  - At each step they choose from the available elements based on their associated *probabilities*
  - Element probability is a function of heuristic information (eg, estimated cost) and pheromone information (from other ants)
  - Pheromone biases search towards solution characteristics that have proved valuable in the past

# Foraging behaviour of Ant Colonies



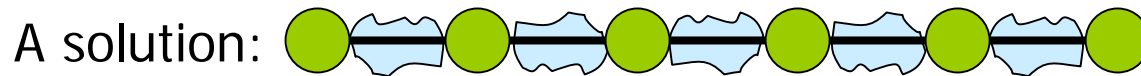
# Ant Colony Optimisation (ACO)

*ACO learns* based on solutions encountered  
in the past

Learning occurs through pheromone, so choosing an appropriate pheromone representation is crucial to the success of an ACO algorithm

# Application of ACO

- Ant System (AS, the first ACO algorithm) associate pheromone and heuristic information with *links*

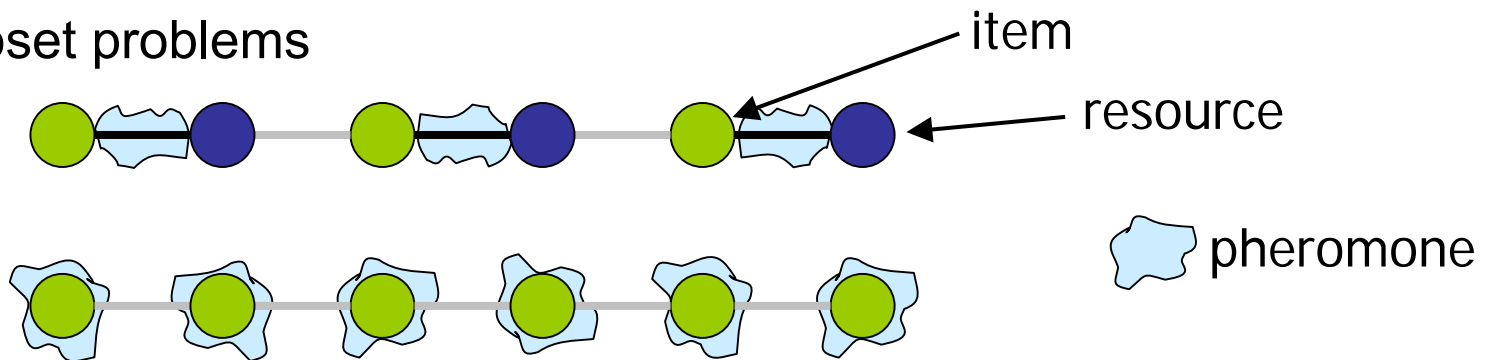


 pheromone

- High degree of similarity between real ants on the ground and artificial ants on a graph
- There are improved ways to apply ACO, like ACS (Ant Colony System)

# Application of ACO

- Initial ACO applications on problems that could be modelled as graphs
  - pheromone associated with *edges* of these graphs
- ACO increasingly applied to problems that don't have a natural graph representation
  - Assignment problems
  - Subset problems



# ACO Techniques

	AS	ACS
Pheromone Update	At the end of the solution, each ant perform an update of each column chosen by this ant.	<p>Two phases:</p> <ul style="list-style-type: none"> <li>- Local Update: The pheromone of the chosen column is modified.</li> <li>- Global Update: The pheromone level of the columns founded in the best solution is modified.</li> </ul>
Transition Rule	It is based in the probability of each column.	<p>Has two points of decision:</p> <ul style="list-style-type: none"> <li>- Use of a list of candidates, which contains the best columns to be chosen according to some creterion.</li> <li>- Use of a parameter <math>q</math>, which indicates if it is used the exploitation of the knowledge or if it is used the exploration of the neighborhood.</li> </ul>

# ACO for SPP

- ACO can be applied in a very straightforward way to the SPP. The columns are chosen as the solution components and have associated a cost and a pheromone trail.
- Constraints say that each column can be visited by an ant once and only once and that a final solution has to cover all rows.
- A walk of an ant over the graph representation corresponds to the iterative addition of columns to the partial solution obtained so far.
- Each ant starts with an empty solution and adds columns until all rows are covered. A column to be added is chosen with a probability that depends of pheromone trail and the heuristic information.

# Construction Phase

Each ant  $k$  chooses the next column  $j$  using the probability given by

$$p_j^k = \frac{[\tau_j]^* [n_j]^\beta}{\sum_{l \in N^k} [\tau_l]^* [n_l]^\beta} \quad \text{si } j \in N^k$$

And updates the chosen columns, according to the Evaporation Rule

$$\tau_j = (1 - \rho)\tau_j + \rho\tau_0$$

# Pheromone Update ( $\tau$ )

- Update when ant chooses element j

$$\tau_j = (1 - \rho)\tau_j + \rho\tau_0$$

- Update at end of iteration for each column in the best solution

$$\tau_j = (1 - \rho)\tau_j + \rho\Delta\tau_j$$

where  $\Delta\tau_j$  is the frequency of the column j in the solutions of the ants

# ACO Procedure for SPP

```
1 Procedure ACO_for_SPP
2 Begin
3   initParameters();
4   While (remain iterations) do
5     For k := 1 to h := nants do
6       While (solution have no completed) do
7         Choose next Column j with Transition Rule Probability
8         addToTabuList(j);
9         For each Row i covered by j do
10          AddColumnToTabuList(j);
11        EndFor
12      EndWhile
13    EndFor
14    updateOptimum();
15    updatePheromone();
16  EndWhile
17  return best_solution_founded
18 End.
```

# Heuristic Information ( $\eta$ )

- To use the actual knowledge (as a transition rule), it is used a dynamic heuristic information that depends on the partial solution of an ant. It is defined as

$$\eta_j = \frac{e_j}{c_j}$$

- Where  $e_j$  is the number of additional rows covered adding a column  $j$  and  $c_j$  is the cost of column  $j$ .

# Pure ACO with limited effectiveness

	$x_1$	$x_2$	$x_3$	$x_4$
1	1	1	0	1
2	0	1	0	0
3	0	0	1	1

## *Constraints*

$$x_1 + x_2 + x_4 = 1$$

$$x_2 = 1$$

$$x_3 + x_4 = 1$$

# Pure ACO with limited effectiveness

- 1st try.

$$\begin{aligned}x_1 = 1 &\rightarrow x_2 = 0 \\ &x_4 = 0\end{aligned}$$

→ Doesn't respect  
Constraint 2

→ Solution cannot  
be completed

- 2nd try.

$$\begin{aligned}x_2 = 1 &\rightarrow x_1 \text{ and } x_4 = 0 \text{ (applying constraint 1)} \\ &x_3 = 1 \text{ (applying constraint 3)}\end{aligned}$$

Solution Found :  $x_1 = 0$   
 $x_2 = 1$   
 $x_3 = 1$   
 $x_4 = 0$

# Constraint Programming (CP)

- CP is used in the variable selection process. It means that now, the column to be added in the solution, will be chosen only if doesn't cause a conflict with the next column to select.
- CP in ACO: **Forward Checking**

# ACO with FC

- Some efforts have been done in order to integrate CP techniques to ACO algorithms.
- Forward Checking (FC) seems to be the easiest way to prevent future conflicts.
- Adding Forward Checking to ACO means that columns are chosen if they do not produce any conflict with respect to the next column to be chosen.
- Forward checking checks only the constraints between the current variable and the future variables: Arc consistency to the not yet instantiated variables.

# Constraint Programming (CP)

```
1 Procedure ACO+CP_for_SPP
2 Begin
3   initParameters();
4   While (remain iterations) do
5     For k := 1 to h := nants do
6       While (solution have no completed) do
7         Choose next Column j with Transition Rule Probability
8         For each Row i covered by j do           /*Constraint with j*/
9           feasible(i):=Posting(j);                 /*Constraint Propagation*/
10        EndFor
11        If feasible(i) for all i then
12          AddColumnToSolution(j)
13        Else
14          Backtracking(j)                           /*Set j uninstantiated*/
15        AddColumnToTabuList(j);
16      EndWhile
17    EndFor
18    updateOptimum();
19    updatePheromone();
20  EndWhile
21  return best_solution_founded
22 End.
```

# Experiments and Results

- Adding FC and FLA techniques to the basic ACO algorithms for solving standard benchmarks taken from the Beasley's ORLIB.
- Considering several tests and published experimental results we use the following parameters for the algorithms:  $\rho = 0.4$ , number of iterations = 160, number of ants = 120,  $\beta = 0.5$ , for ACS  $Q_0 = 0.5$
- Algorithms were implemented using ANSI C, GCC 3.3.6, under Microsoft Windows XP Professional version 2002.



# Experiments and Results

- The effectiveness of hybridization is showed to some instances of SPP solving with AS+FC
- Strongly constrained problem characteristic of SPP does the stochastic behavior of ACO improved with FC techniques in the construction phase, so that almost only feasible solutions are induced
- In the original ACO implementation the SPP solving derives in a lot of unfeasible labeling of variables, and many ants can not complete solutions

# Conclusions

- Performance of ACO is possible to improve with some classes of hybridization
- Using only the transition rule of pure ACO doesn't allow, in some problems, to complete feasible solutions
- In a restricted problem like SPP, ACO with Lookahead techniques showed an interesting performance, we demonstrated that this integration improves the process, mainly with respect to success costs instead running times. But the trade off in all cases is very convenient

# Future Work

- To study the pheromone representation and will try to incorporate it into Lookahead techniques
- Considering that the ant's solutions may contain redundant components which can be eliminated by a fine tuning after the solution, then we will explore Post Processing procedures, which consist in the identification and replacement of the columns of the ACO solution in each iteration by more effective columns
- To study available local search techniques in order to reduce the input problem and improve the solutions given by the ants